

Exam CT4150 Plastic Analysis of Structures
 Thursday 26 January 2012, 14:00 – 17:00 hours

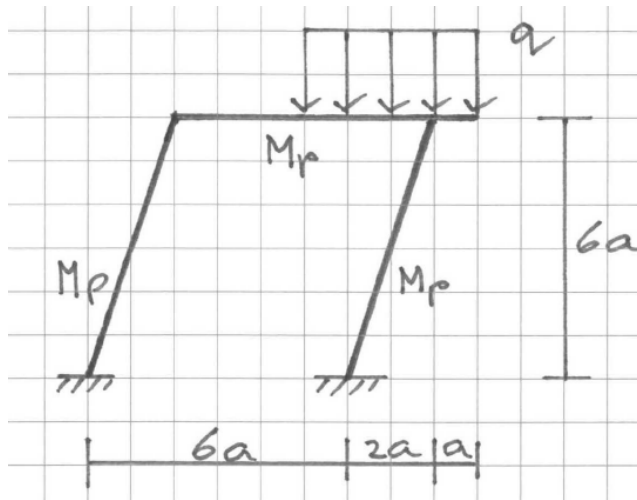


Figure 1. Frame structure

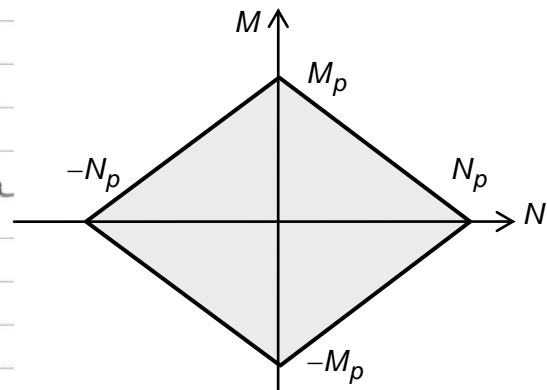


Figure 2. Yield contour

Problem 1

A frame consists of two columns and a beam (Fig. 1). The joints are fixed connections. The structure is loaded by a vertical load q . The relation of Figure 2 exists between the plastic moment M_p and the plastic normal force N_p .

$$N_p = \beta \frac{M_p}{a}$$

The influence of shear on the yield contour is neglected. Buckling and second order effects are not considered.

- a** Assume $\beta \rightarrow \infty$. Determine the collapse load q for all possible mechanisms. Write the collapse loads as functions of M_p and a . What is the decisive collapse load? (1.5 point)
- b** Assume $\beta \rightarrow \infty$. Draw the bending moment diagram and normal force diagram for the structure at the moment of collapse. (1.5 points)
- c** Assume $\beta = 10$. Choose one of the following problems (You need not do both).
 - Use Figure 3 to determine the largest lower-bound for q .
 - Determine the smallest upper-bound for q .
 You only need to write down the equations and not solve the equations (1.5 points).

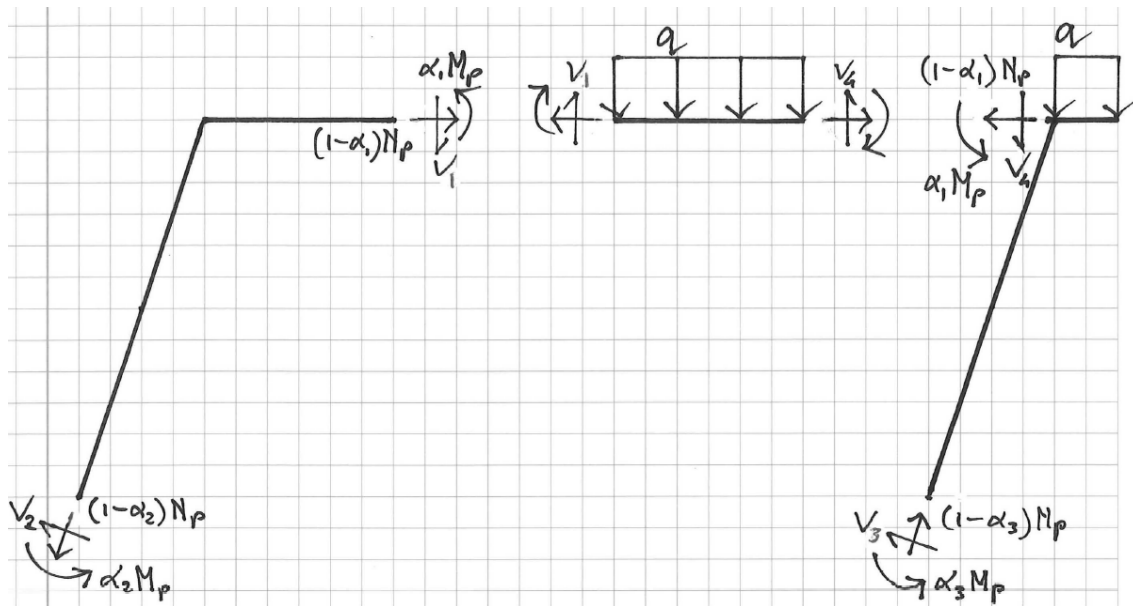


Figure 3. Equilibrium system for including M-N interaction

Problem 2

A reinforced concrete plate has two simply supported edges (Fig. 4). It carries an evenly distributed load q over half of the plate (shaded area). The plate is homogeneous and orthotropic.

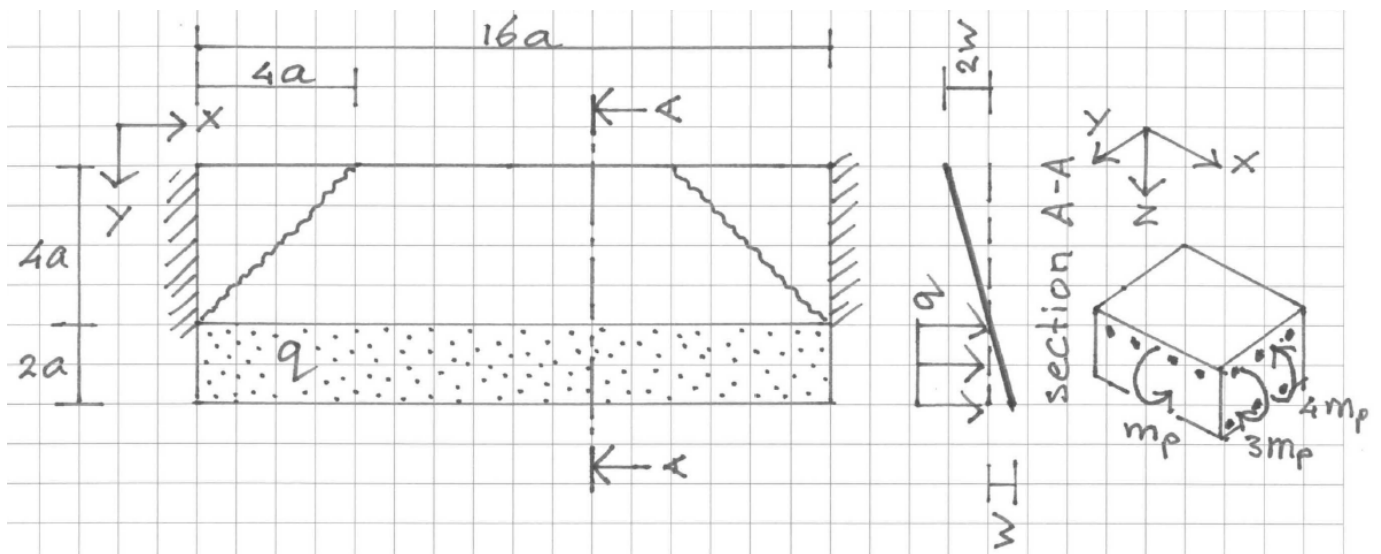


Figure 4. Plate dimensions and reinforcement

- a Consider the yield line patterns of Figure 5. Which of these patterns give kinematically possible mechanisms? (1 point)

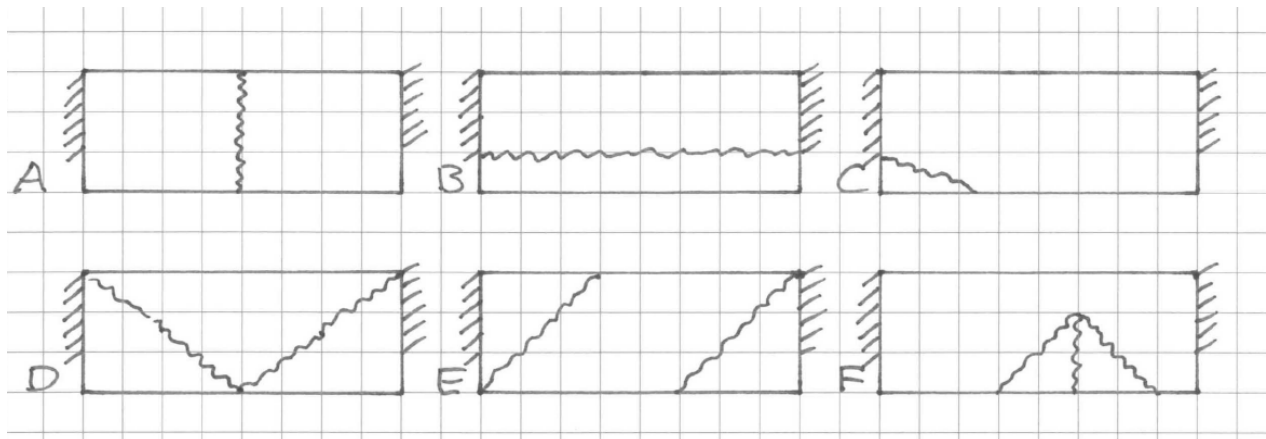


Figure 5. Yield line patterns of problem 2a

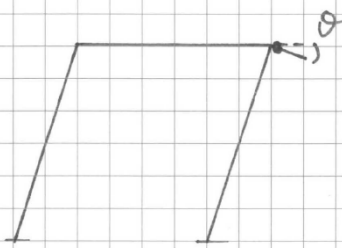
- b** Consider the yield line pattern of Figure 4. Determine an upper bound for q expressed in m_p and a (1.5 point).
- c** Determine the largest lower-bound for q using torsion free beams ($m_{xy} = 0$) (1.5 point).

Problem 3

- a** What is the reason for using the rhombic interaction diagram of Figure 2?
Choose A, B, C, or D (0.38 point).
- A This diagram is not so realistic for many sections but always on the safe side.
 - B This diagram is exact for rectangular cross-sections.
 - C This diagram is a very good approximation for Γ -sections which are often applied.
 - D This diagram is mathematically consistent to the virtual work equation.
- b** Which of the following words refers to a different concept than the others?
Choose A, B, C, or D (0.38 point).
- A Interaction diagram
 - B Deformation capacity
 - C Yield contour
 - D Limit state function
- c** The deflection of the centre of gravity of a rigid triangular plate is ...
Choose A, B, C or D (0.38 point).
- A ... one third of the largest deflection.
 - B ... half of the average of the two largest corner deflections.
 - C ... the quotient of the static moment and the surface area.
 - D ... the average of the corner deflections.

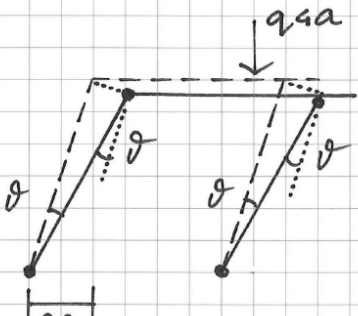
- d** The strength of reinforced concrete plates loaded in bending can be much higher than found in a plastic analysis such as problem 2b. What causes this? Choose A, B, C, or D (0.38 point).
- A Membrane action and arch action.
 - B It is an upper bound analysis and the real strength can be larger.
 - C Safe assumptions are made on the material strengths.
 - D The virtual work equation provides only an approximation of equilibrium.

Answer to Problem 1a



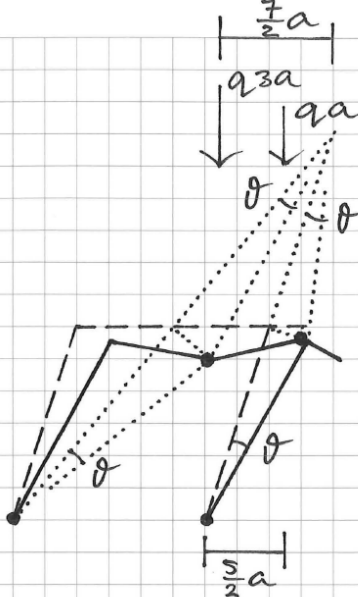
$$E = M_p \theta$$

$$A = q a \frac{1}{2} a \theta$$

$$E = A \Rightarrow q = 2 \frac{M_p}{a^2}$$


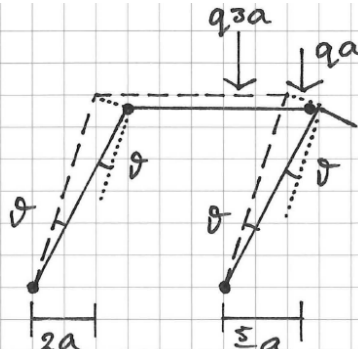
$$E = M_p \theta + M_p \theta + M_p \theta + M_p \theta = 4 M_p \theta$$

$$A = q 4a \theta 2a = 8 q a^2 \theta$$

$$E = A \Rightarrow q = \frac{1}{2} \frac{M_p}{a^2}$$


$$E = M_p \theta + M_p (\theta + \theta) + M_p (\theta + \theta) + M_p \theta = 6 M_p \theta$$

$$A = q a \theta \frac{5}{2} a + q 3a \theta \frac{7}{2} a = 13 q a^2 \theta$$

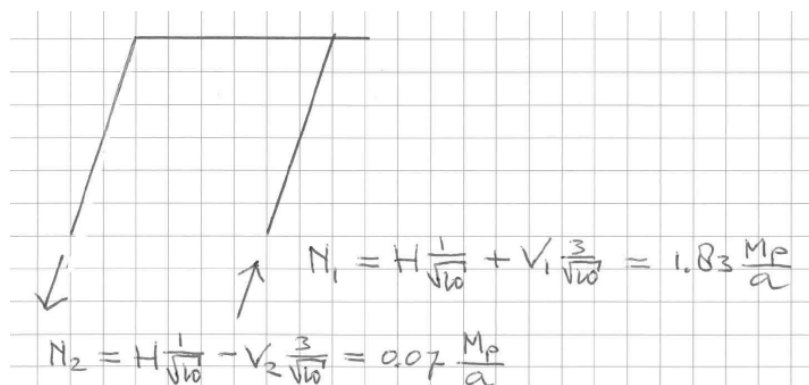
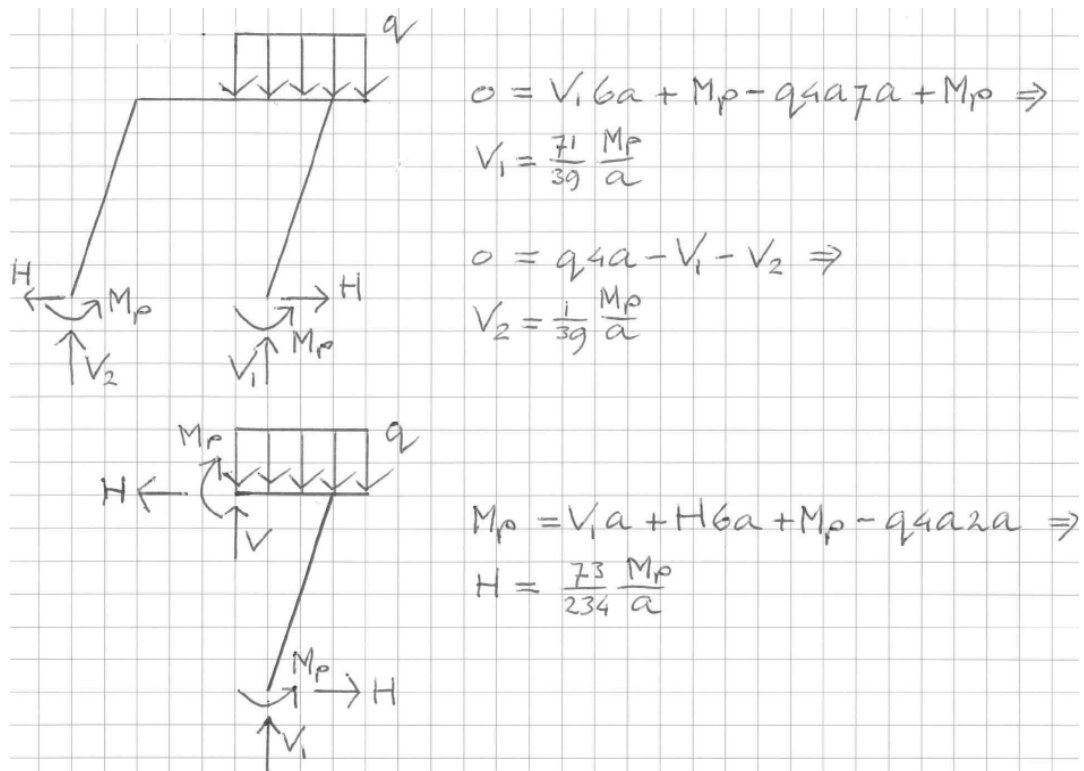
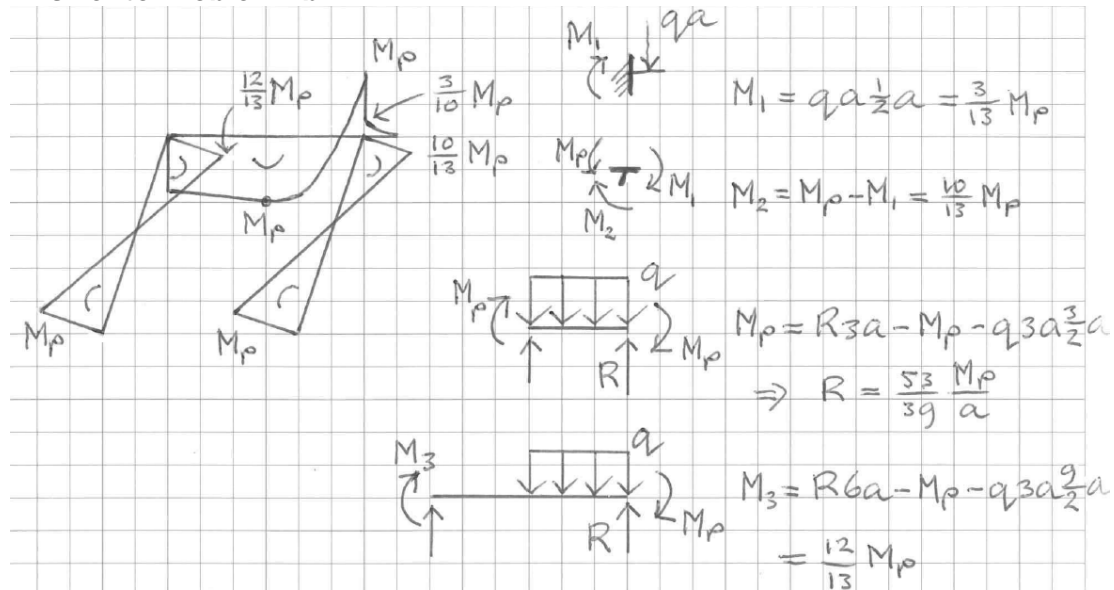
$$E = A \Rightarrow \boxed{q = \frac{6}{13} \frac{M_p}{a^2}} \text{ decisive}$$


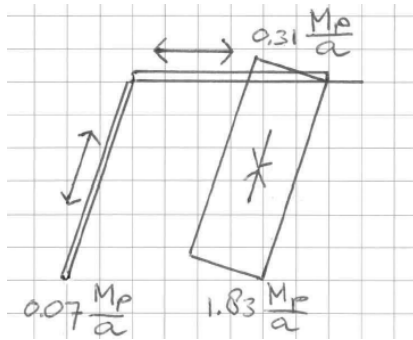
$$E = M_p \theta + M_p \theta + M_p \theta + M_p \theta = 4 M_p \theta$$

$$A = q 3a \theta 2a + q a \theta \frac{5}{2} a = \frac{17}{2} q a^2 \theta$$

$$E = A \Rightarrow q = \frac{8}{17} \frac{M_p}{a^2}$$

Answer to Problem 1b



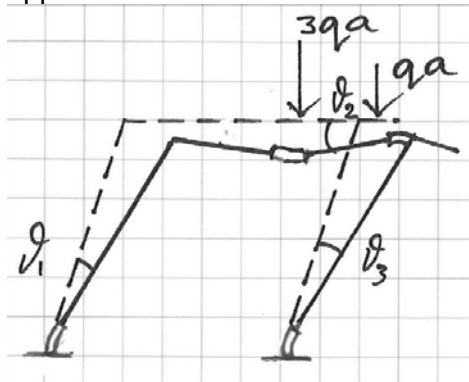


Answer to Problem 1c

lower-bound

```
[> Np:=10.*Mp/a:
[> s:=sqrt(10):
[> eq1:= 0= (1-a1)*Np -V2*3/s - (1-a2)*Np/s:
[> eq2:= 0= V1 - V2/s + (1-a2)*Np*3/s:
[> eq3:= 0= a1*Mp - (1-a1)*Np*6*a -V1*5*a +a2*Mp:
[> eq4:= 0= V1 -q*3*a +V4:
[> eq5:= 0= q*3*a*3/2*a -V4*3*a +a1*Mp +a1*Mp:
[> eq6:= 0= (1-a1)*Np +V3*3/s - (1-a3)*Np/s:
[> eq7:= 0= V4 +q*a - (1-a3)*Np*3/s -V3/s:
[> eq8:= 0= q*a*5/2*a - (1-a1)*Np*6*a +V4*2*a -a1*Mp -a3*Mp:
[> solve({eq1,eq2,eq3,eq4,eq5,eq6,eq7,eq8},{a1,a2,a3,V1,V2,V3,V4,q});
{V1 = 0.01091410889 Mp/a, V2 = 0.3046079498 Mp/a, V3 = 0.2489320127 Mp/a, V4 = 1.301921184 Mp/a,
a1 = 0.9682553065, a2 = 0.9909968498, a3 = 0.8249348610, q = 0.4376117644 Mp/a^2}
```

upper-bound



```
[> b:=10.: s:=sqrt(10):
[> eq1:= t1*a/b/s +t1*6*a + (t1+t2)*a/b = -t3*a/b/s +t3*6*a - (t3+t2)*a/b:
[> eq2:= -t1*a/b*3/s +t1*5*a = t3*a/b*3/s +t3*2*a +t2*3*a:
[> E:= Mp*t1 +Mp*(t1+t2) +Mp*(t2+t3) +Mp*t3:
[> A:= q*a*(t3*a/b*3/s +t3*5/2*a) +3*q*a*(t3*a/b*3/s +t3*2*a +t2*3/2*a):
[> eq3:= E=A:
[> solve({eq1,eq2,eq3},{t1,t3,q});
{q = 0.4376117644 Mp/a^2, t1 = 1.130731235 t2, t3 = 1.215534913 t2}
```

Answer to Problem 2a

A, B, C, D, E, F

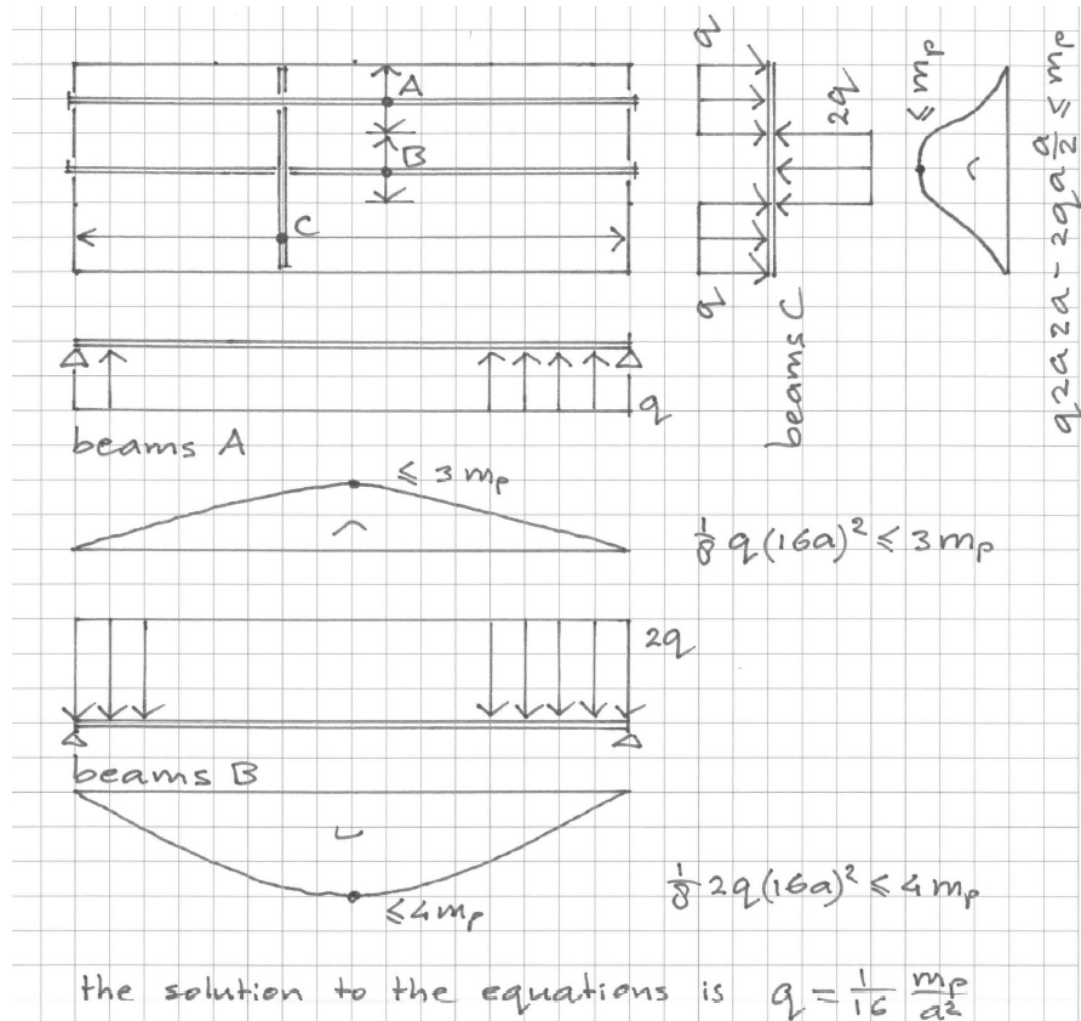
Answer to Problem 2b

$$E = 2 \left[3m_p 4a \frac{2w}{4a} + m_p 4a \frac{2w}{4a} \right] = 16 m_p w$$

$$A = q 2a 16a \frac{w}{2} = 16 q a^2 w$$

$$E = A \Rightarrow q = \frac{m_p}{a^2}$$

Answer to Problem 2c



Answer to Problem 3a

A

Answer to Problem 3b

B

Answer to Problem 3c

D

Answer to Problem 3d

A